

# Data assimilation of rheology on ice shelves in Antarctica using a new finite element formulation of rifting and faulting processes.



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Effort funded by NASA MAP 08.



12/16/2009



# Outline

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3. Ice rheology Brunt Ice Shelf.
4. Ice rheology Larsen C Ice Shelf.
5. Conclusions.

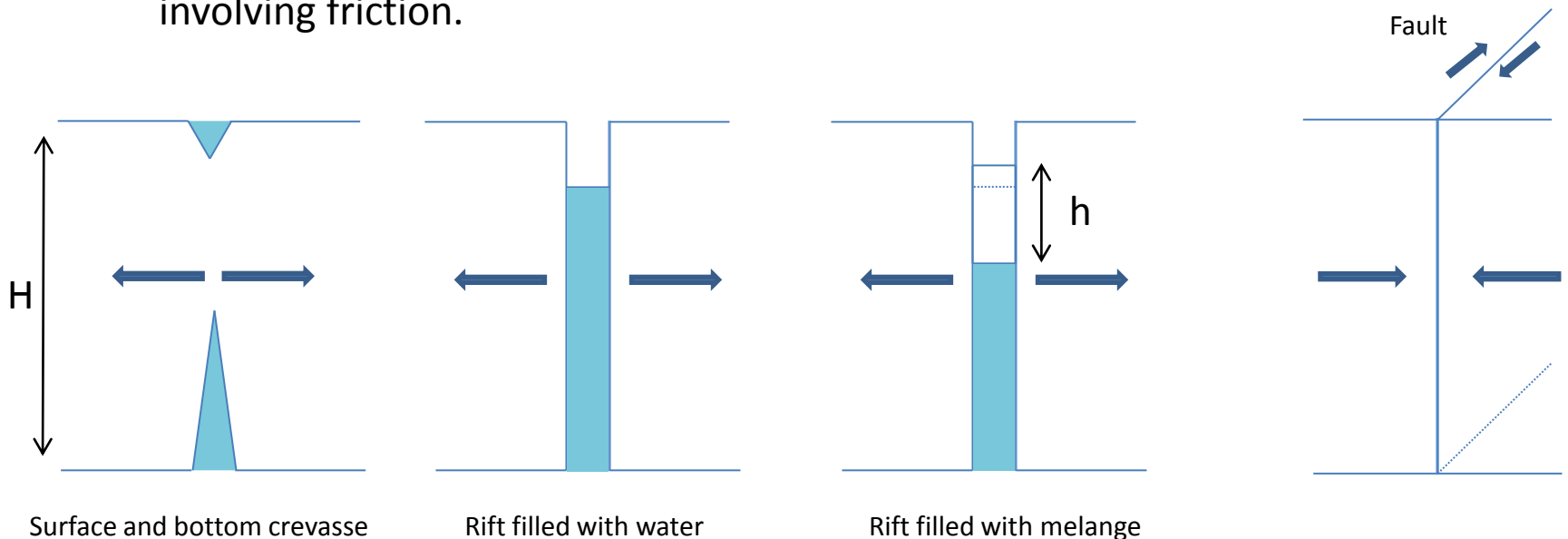
# 1 Introduction

- Crevasses that penetrate through thickness create rifts that influence ice flow on ice shelves in a major way.
- Rifts can close when longitudinal stresses become compressive enough -> rifts become faults where tangential friction along flanks drives ice flow.
- Rifts filled with water are inherently unstable (when non-linear creep flow law is considered) -> wiggling between rift and fault state. Melange stabilizes this process.
- We present new finite element model, embedded into ISSM (Ice Sheet System Model), to model contact mechanics of faults, and ice flow around rifts filled with melange.
- We apply this new model to invert for ice rheology on Brunt Ice Shelf and Larsen C Ice Shelf.

# 2 Rift/Fault modeling.

Several types of rifts/faults can be observed in ice shelves:

- surface and bottom crevasses in the process of creating rifts.
- rifts filled with water or melange: opening flanks on both sides of the rift.
- fault: rift that stopped opening and is closing, with contact between both flanks, involving friction.



Boundary conditions for opening rift:

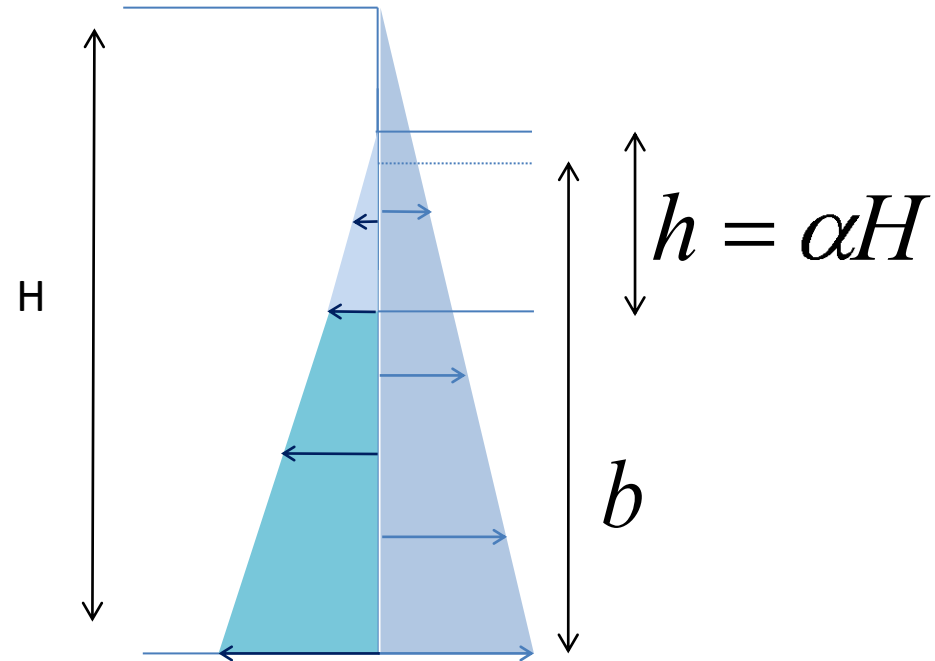
$$P = P_{litho} - P_{air} - P_{melange} - P_{water}$$

$$P_{litho} = \frac{\rho_{ice} g H^2}{2}$$

$$P_{water} = \frac{\rho_{water} g \left[ b^2 - \left( \frac{\rho_{ice}}{\rho_{water}} \alpha H \right)^2 \right]}{2}$$

$$P_{melange} = \frac{\rho_{ice} g (\alpha H)^2}{2}$$

$$P_{air} = 0$$



For  $\alpha = 0 \rightarrow$  ice front.

$$P = \frac{\rho_{ice} g H^2}{2} - \frac{\rho_{water} g b^2}{2}$$

For  $\alpha = 1 \rightarrow$  rift fully filled with ice.

$$P = 0$$

For a rift filled with water, imbalance between ice and water pressure tends to close rift.

For a rift filled with ice, pressure is fully compensated, and opening is favored, provided longitudinal stress is tensile.

Boundary conditions for closing fault:

Penalized normal penetration:

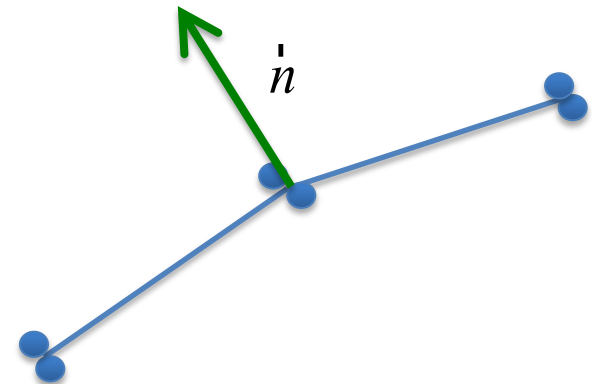
$$\sigma_n = -K_{\max} 10^{\lambda} \Delta V_n$$

$$Kn = K_{\max} 10^{\lambda} \begin{bmatrix} n_x^2 & n_x n_y & -n_x^2 & -n_x n_y \\ n_x n_y & n_y^2 & -n_x n_y & -n_y^2 \\ -n_x^2 & -n_x n_y & n_x^2 & n_x n_y \\ -n_x n_y & -n_y^2 & n_x n_y & n_y^2 \end{bmatrix}$$

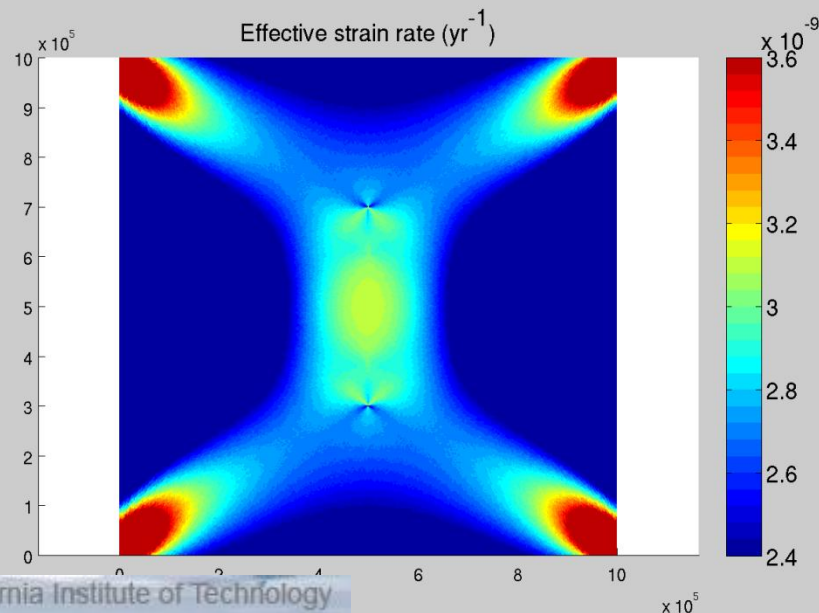
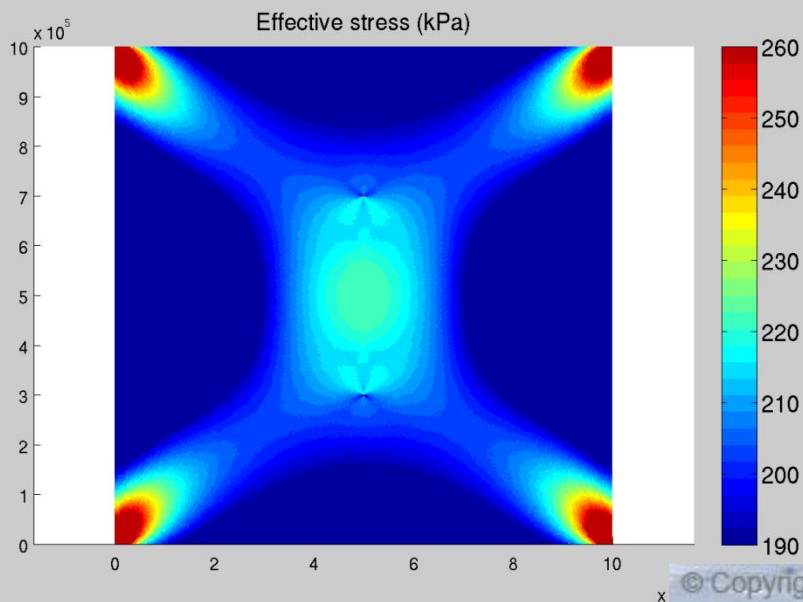
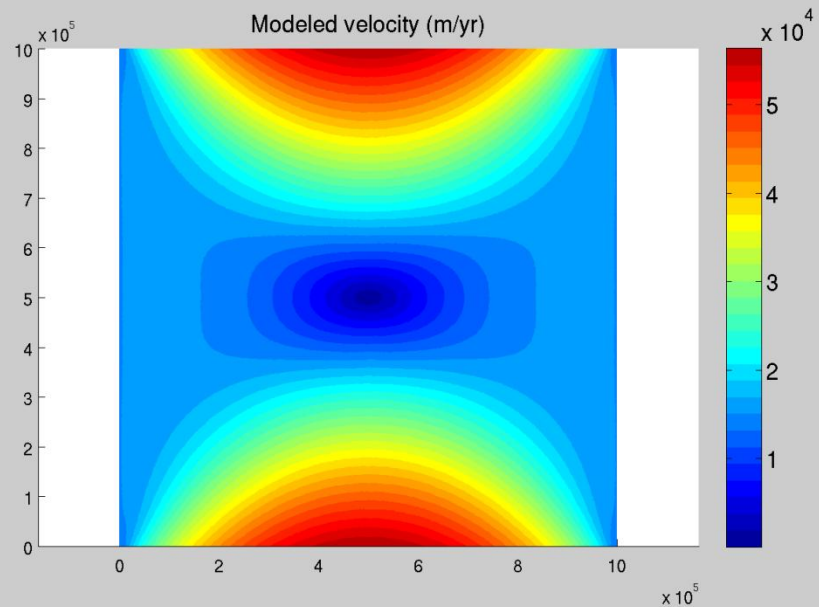
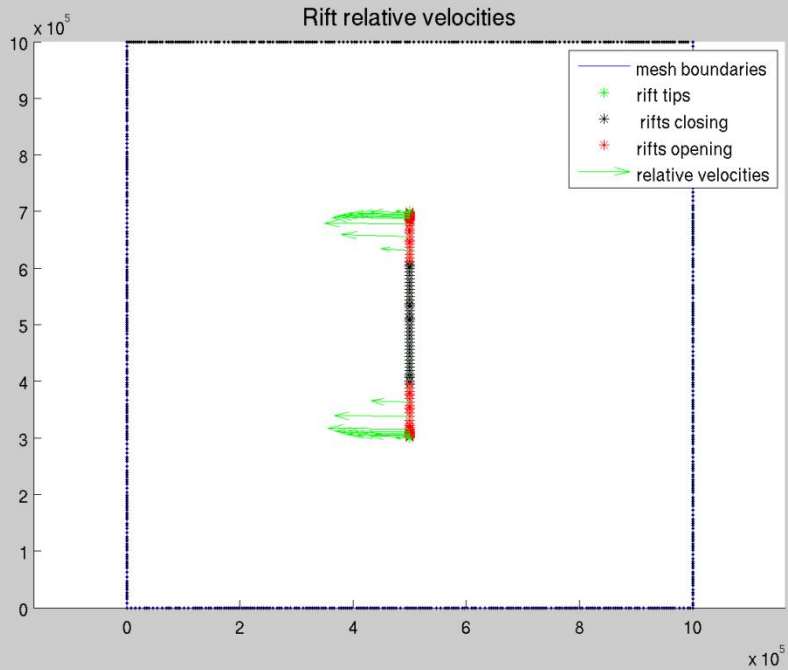
Tangential linear friction:

$$\sigma_t = f * H * l * \Delta V_t$$

$$Kt = H.l.f \begin{bmatrix} n_y^2 & -n_x n_y & -n_y^2 & n_x n_y \\ -n_x n_y & n_x^2 & n_x n_y & -n_x^2 \\ -n_y^2 & n_x n_y & n_y^2 & -n_x n_y \\ n_x n_y & -n_x^2 & -n_x n_y & n_x^2 \end{bmatrix}$$



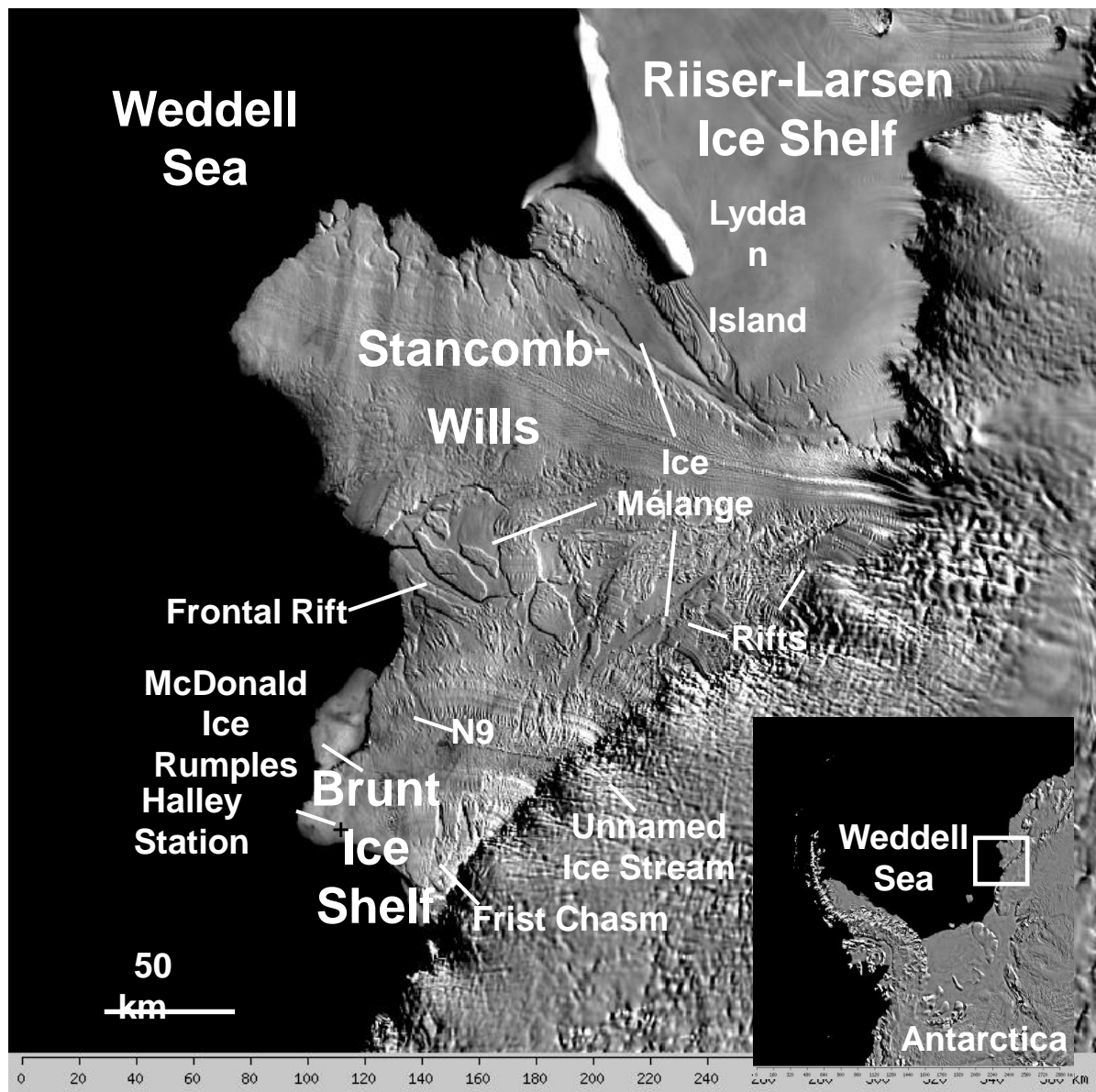
$K_{\max}$ : maximum stiffness matrix  
 $\lambda$ : penalty offset.  
 $H$ : ice thickness  
 $l$ : segment length  
 $f$ : friction coefficient.

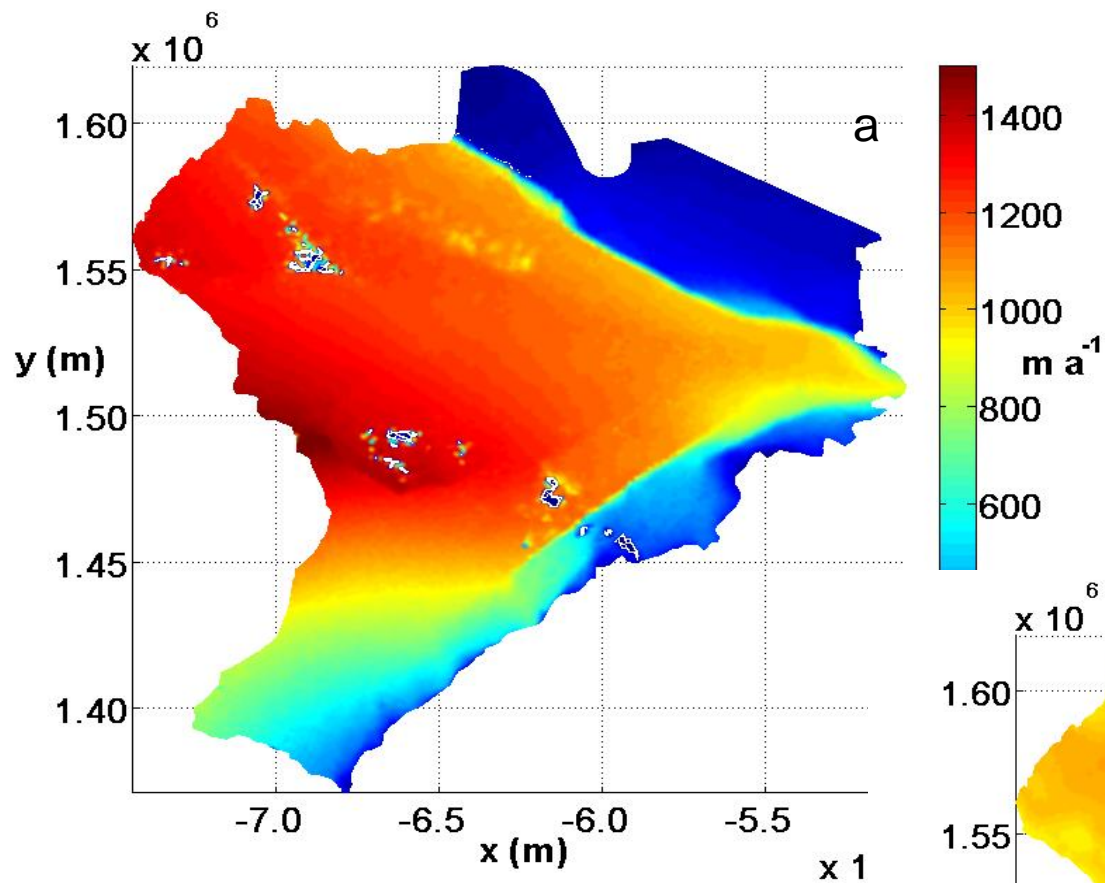




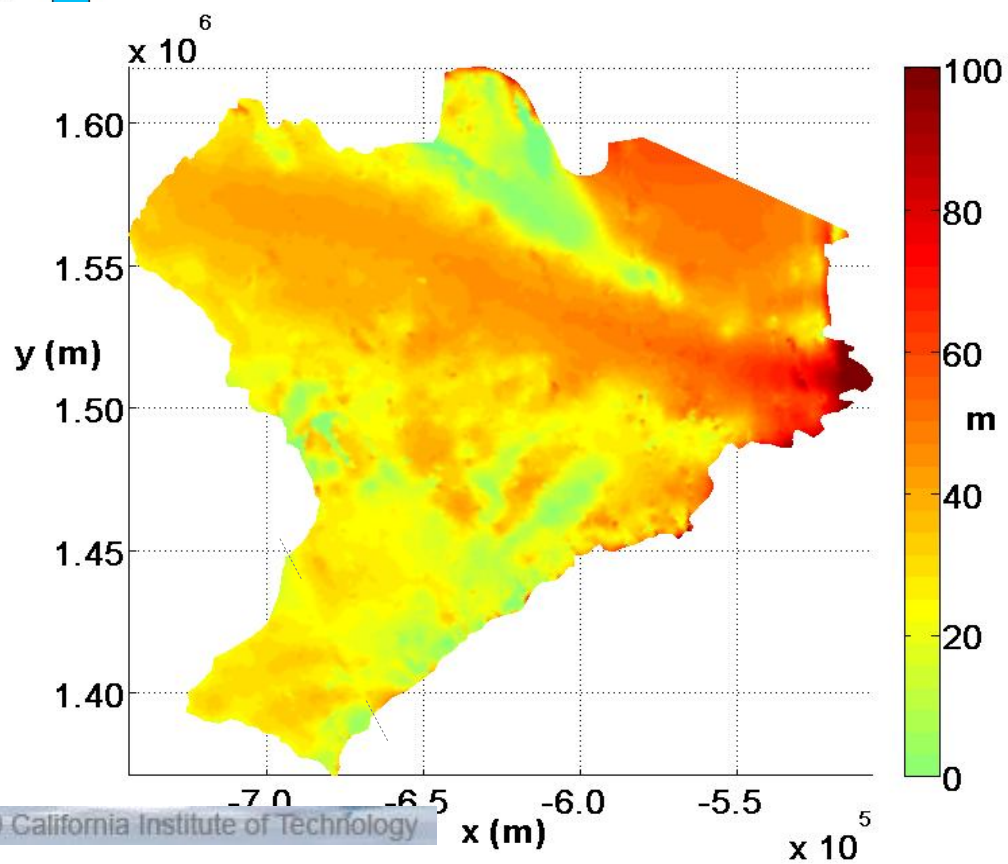
# 3 Brunt Ice Shelf.

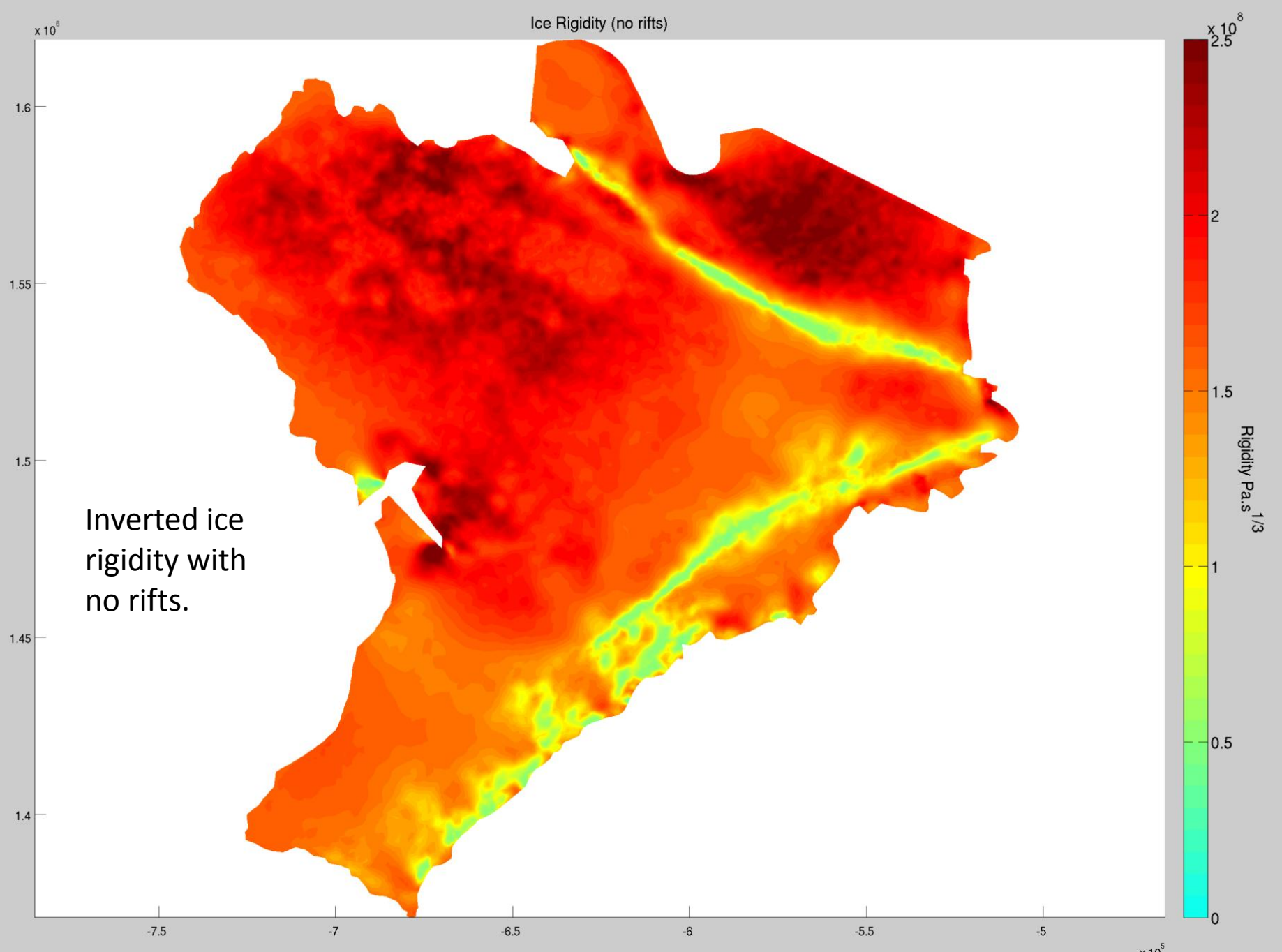
- Radarsat-1 speckle-tracking surface velocity acquired in 2000.
- Grounding line inferred from ERS-1/2 data (from 1996 for fast flow areas) and RADARSAT-1 (from 2000 for slower moving areas) using double difference Interferometry.
- Ice shelf elevations from the GLAS/ICE Sat laser altimeter digital elevation model of Antarctica [DiMarzio et al., 2007].
- Firn estimates from van den Broeke [2006, 2008].





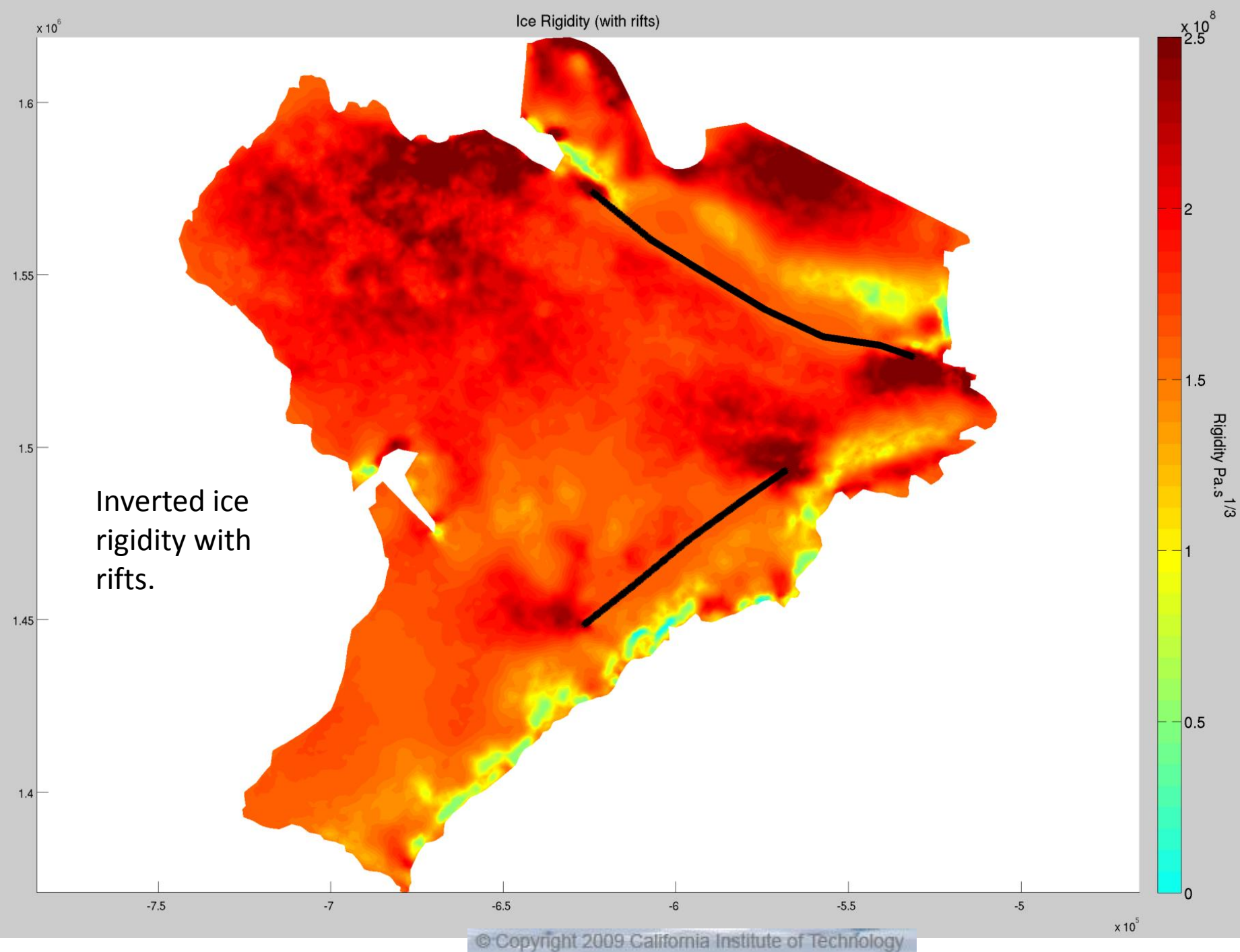
Surface DEM.

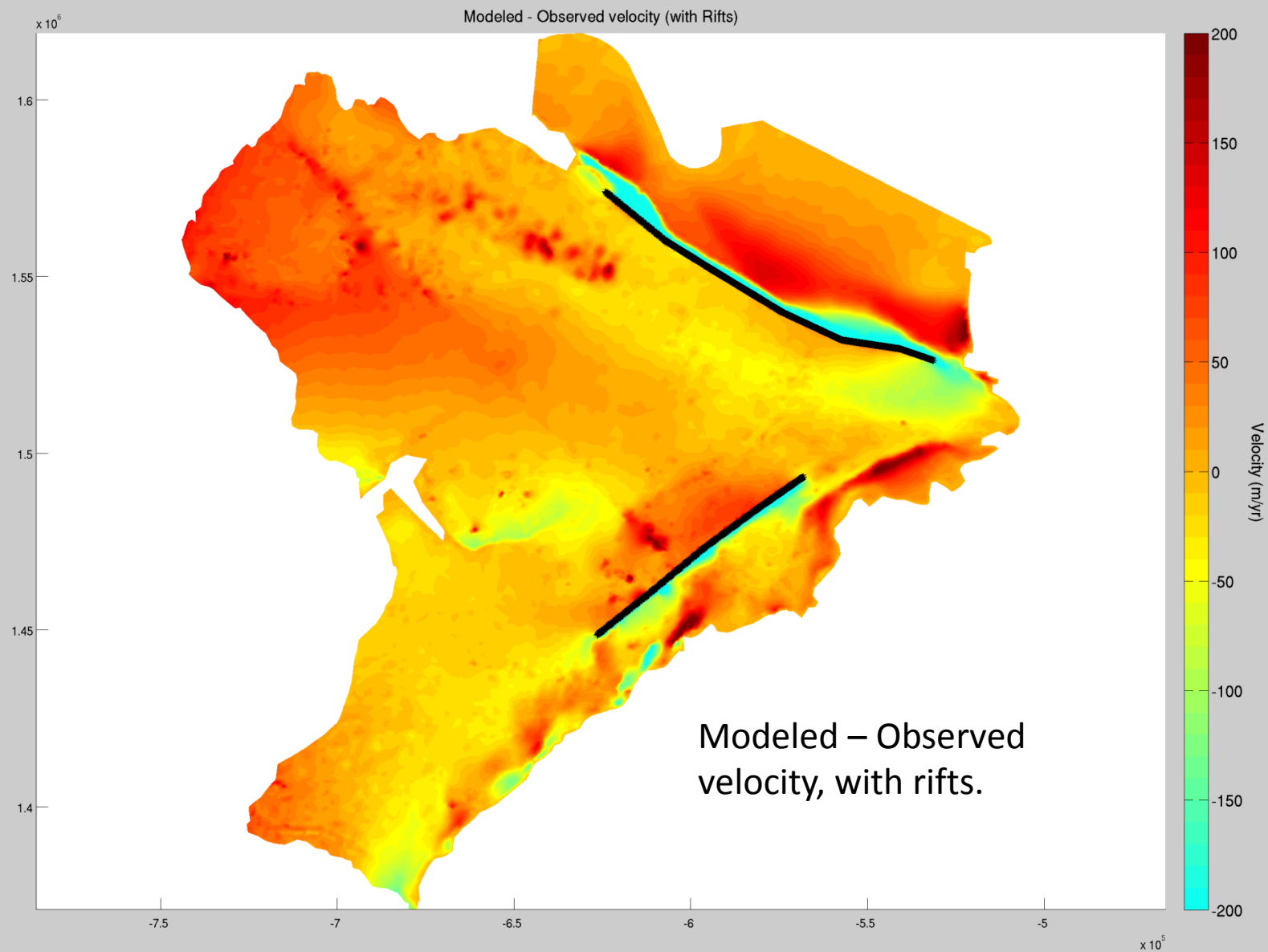


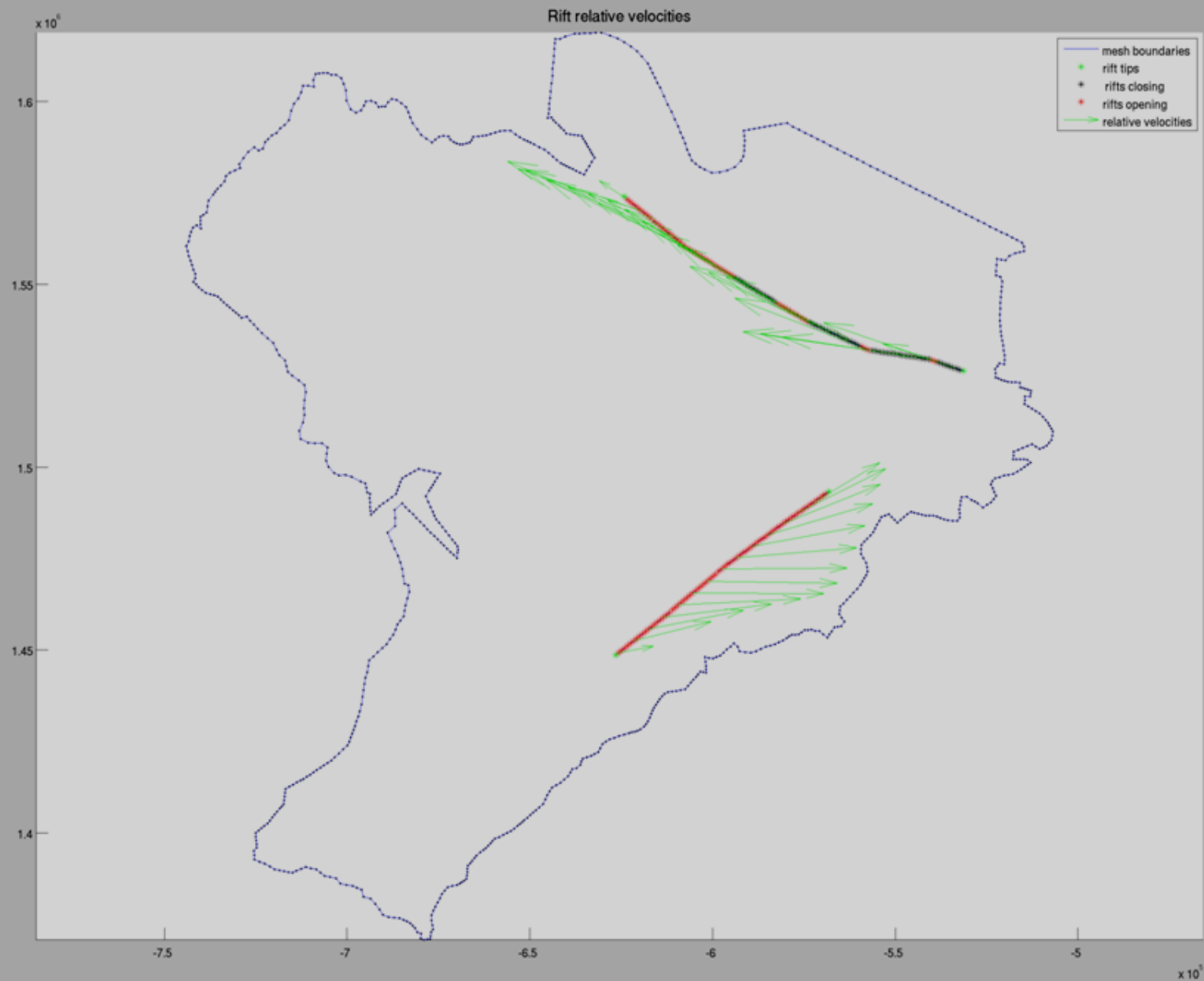


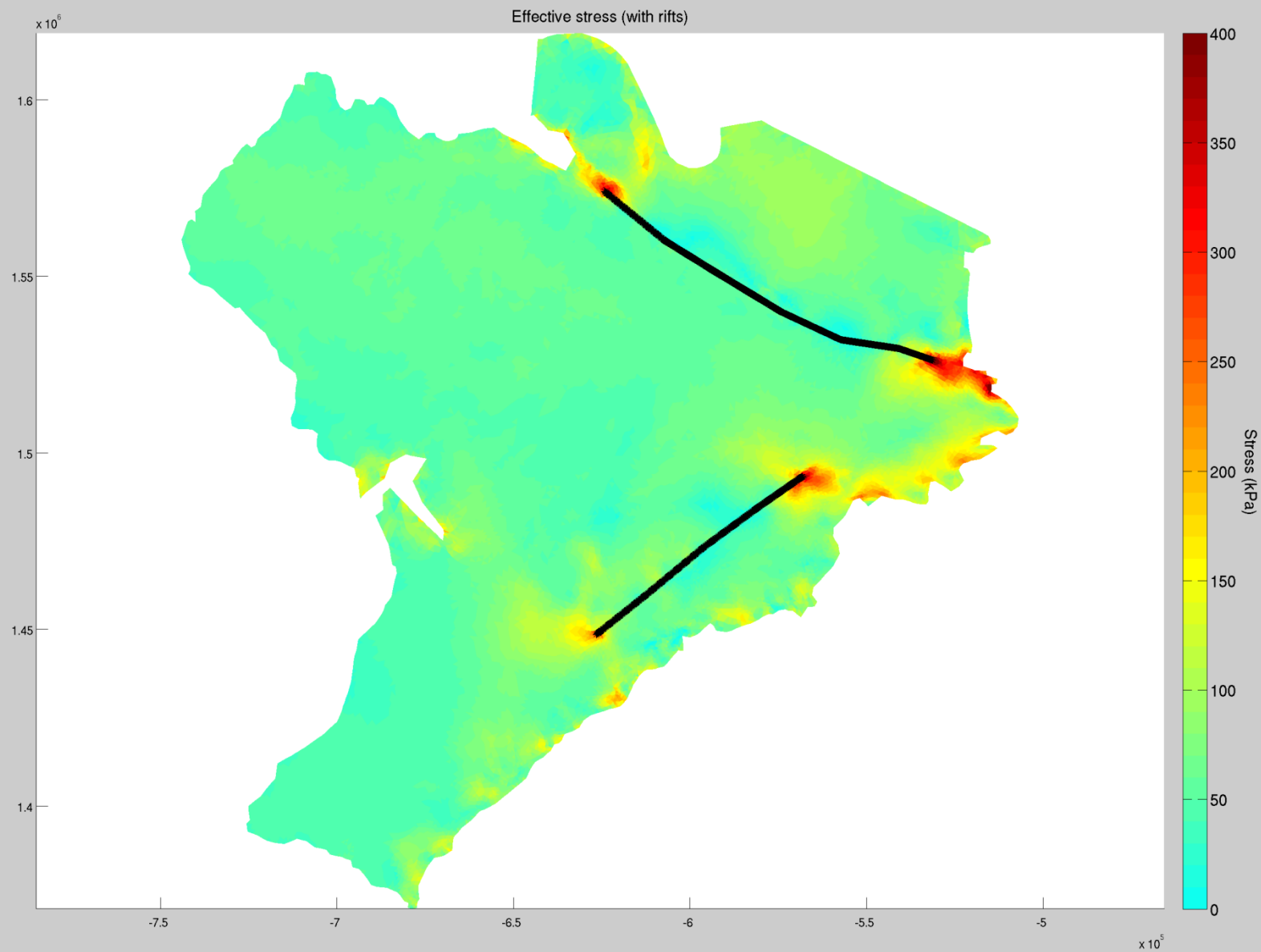


Ice Rigidity (with rifts)



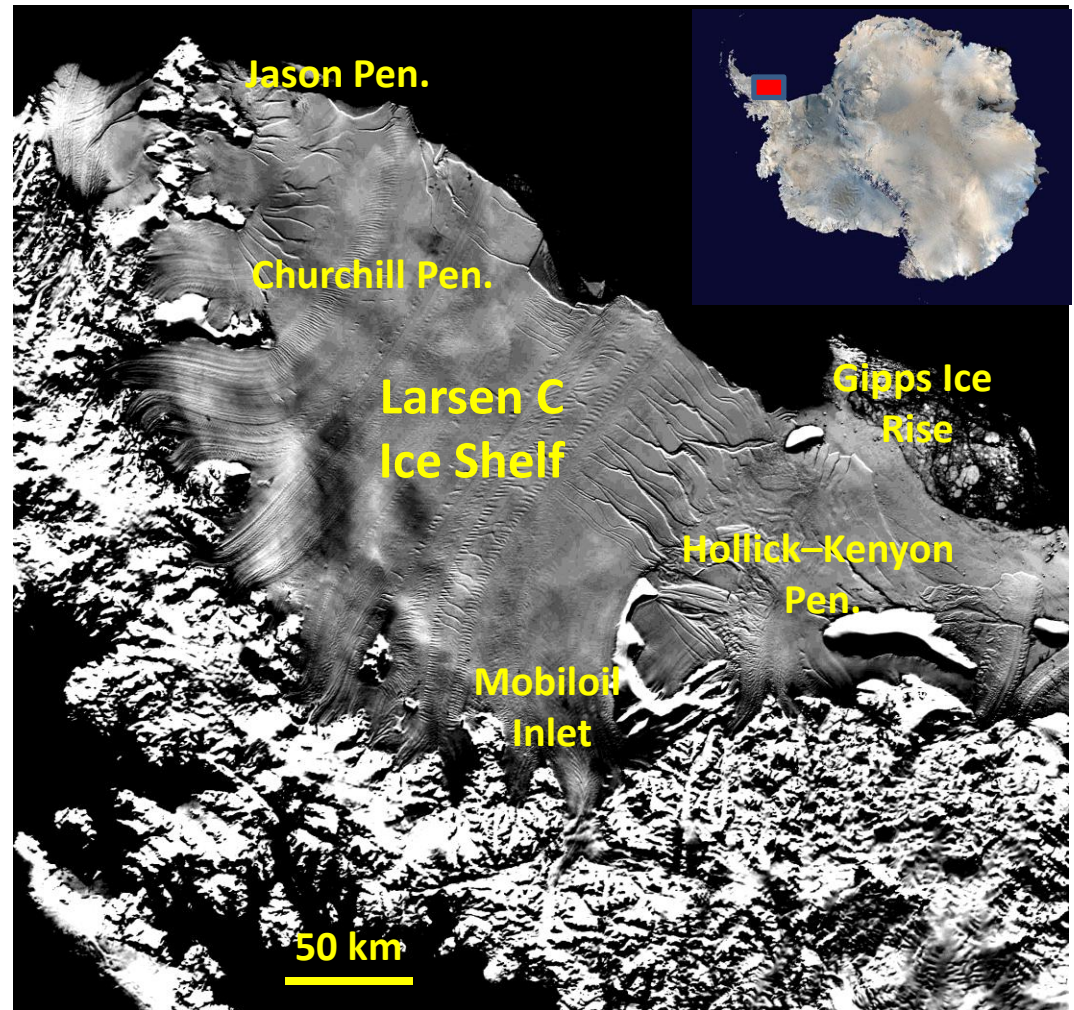




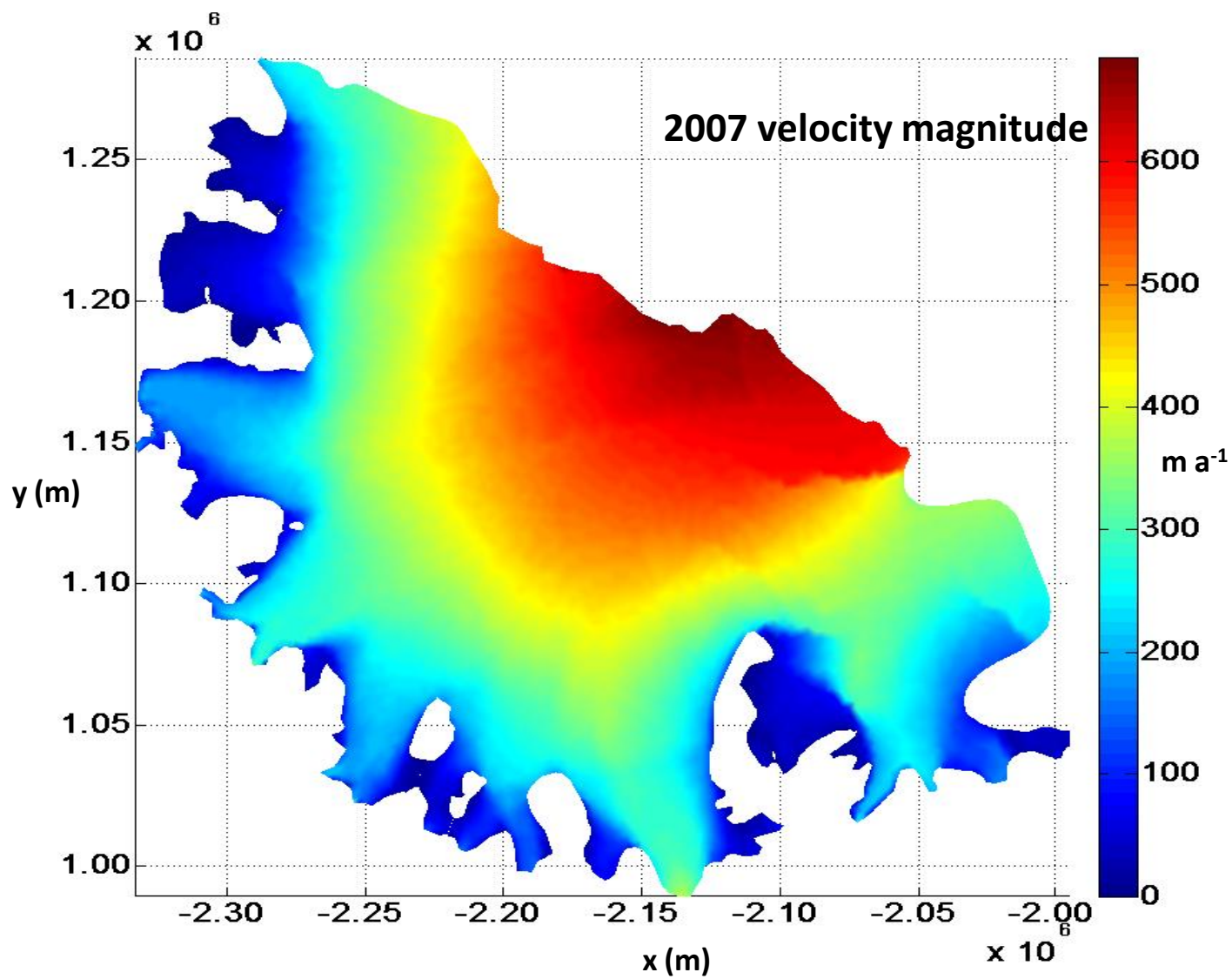


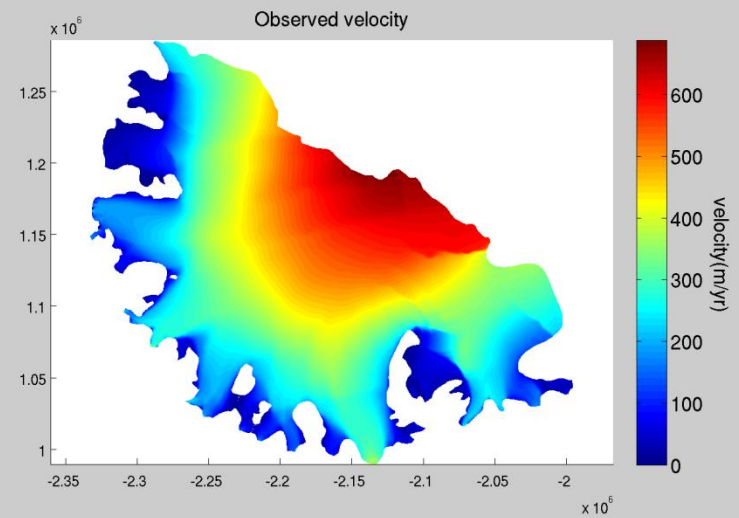
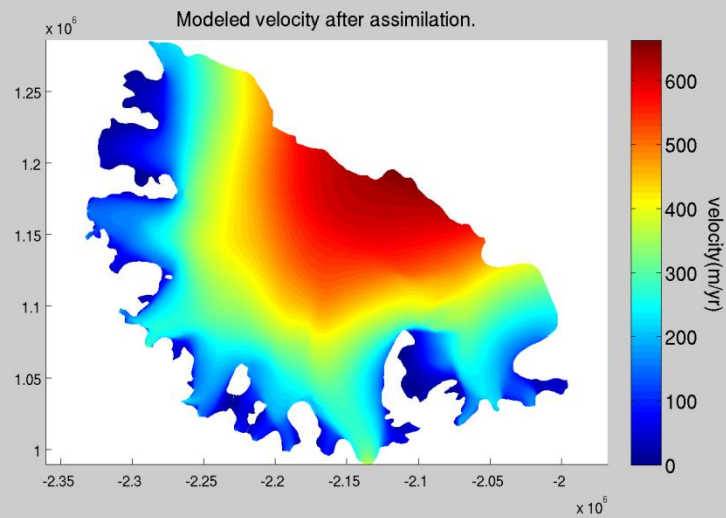
# 4 Larsen C Ice Shelf.

- Ice thickness by *Griggs and Bamber* (2009) obtained from ERS-1 RA data. Corrections made for tidal movement and firn. Resolution = 1 km. Mean random error = 47.3 m.
- Grounding line by double difference interferometry on ERS-1/2 data (march 1996). Error:  $\pm 100$  m.
- Year 2007 (Oct.-Dec.) ice velocity by speckle tracking on ALOS PALSAR data. Error:  $\pm 5$  m a<sup>-1</sup>.

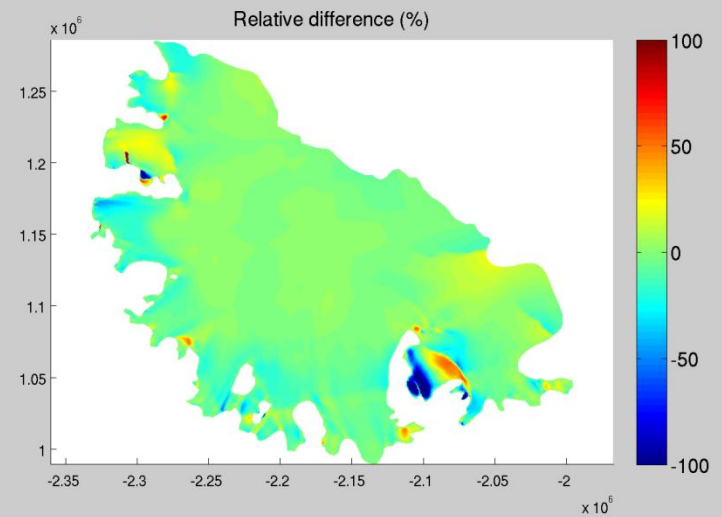
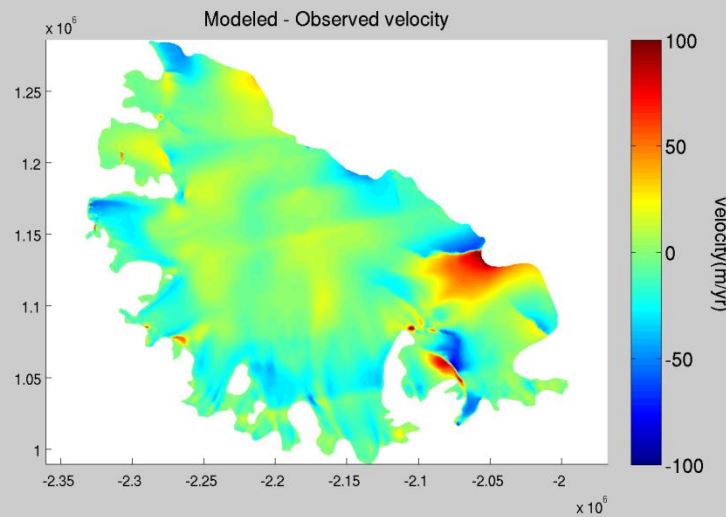


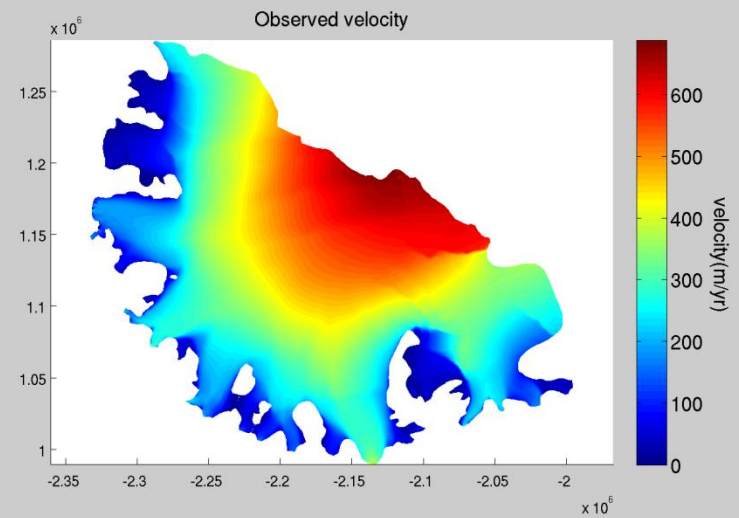
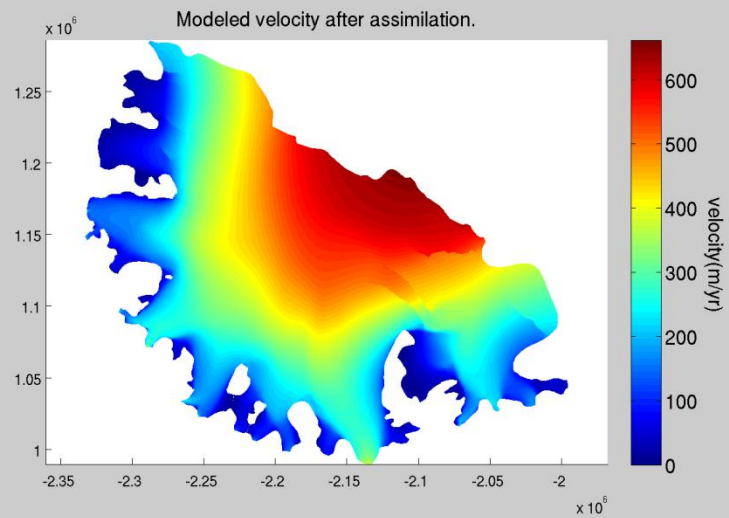




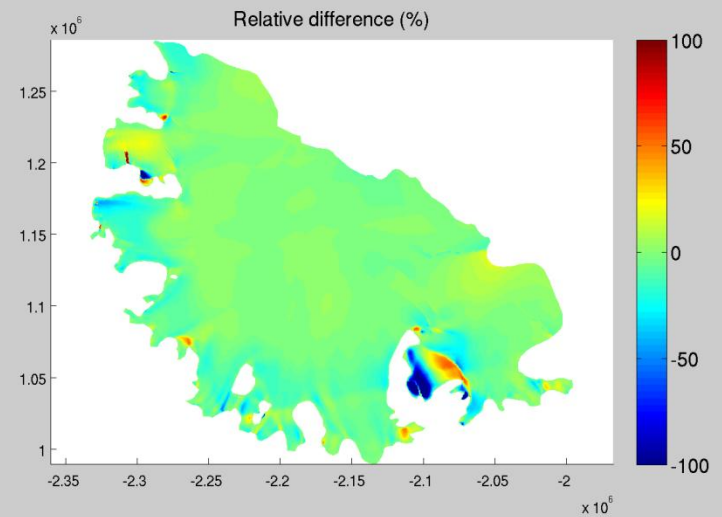
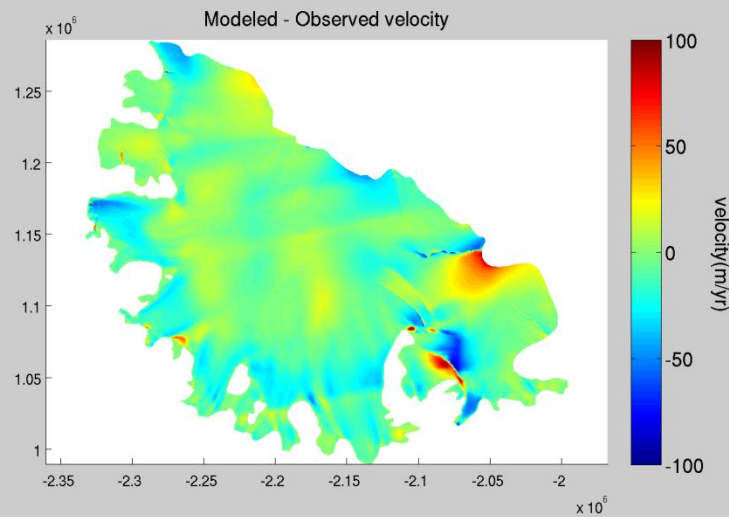


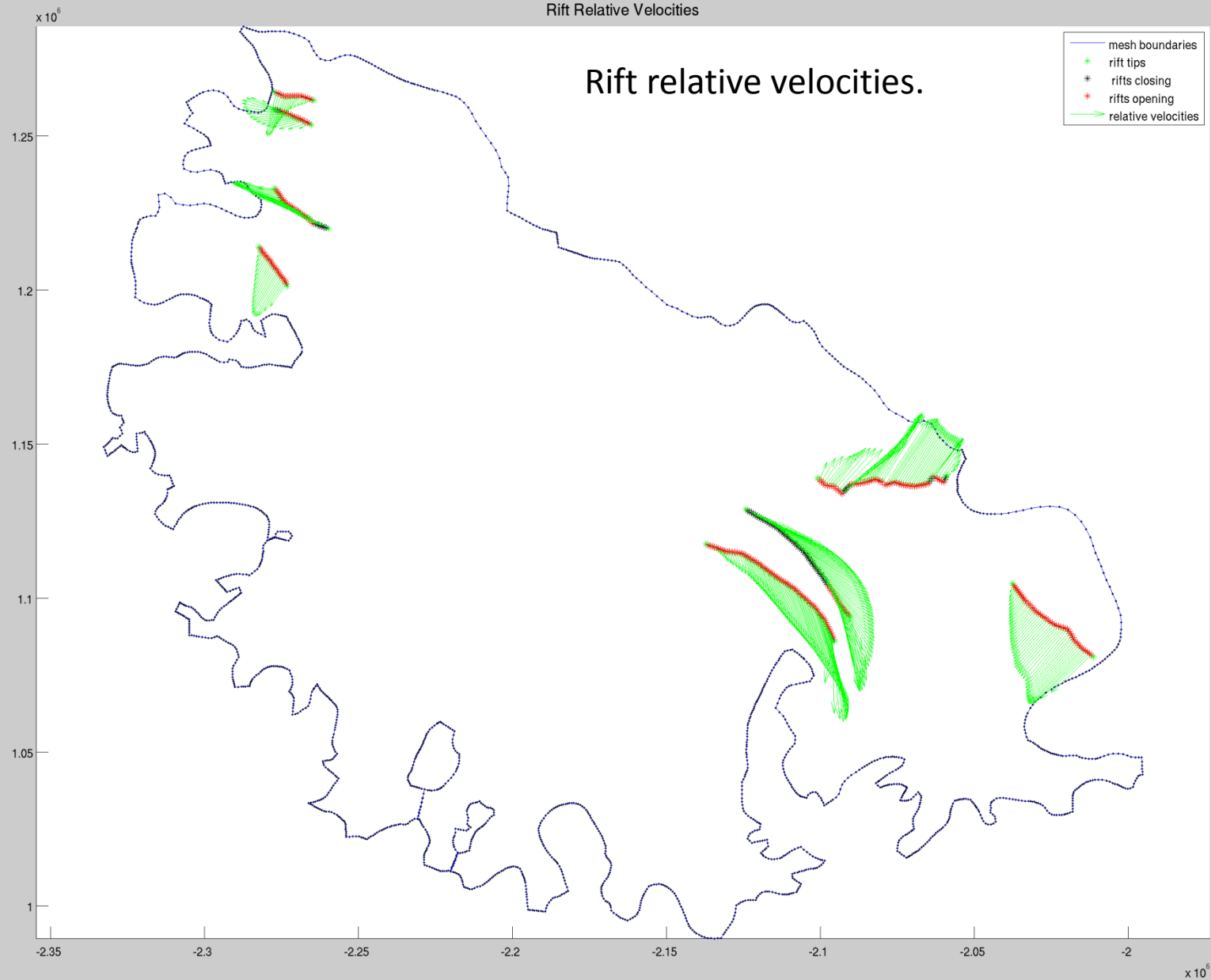
No Rifts

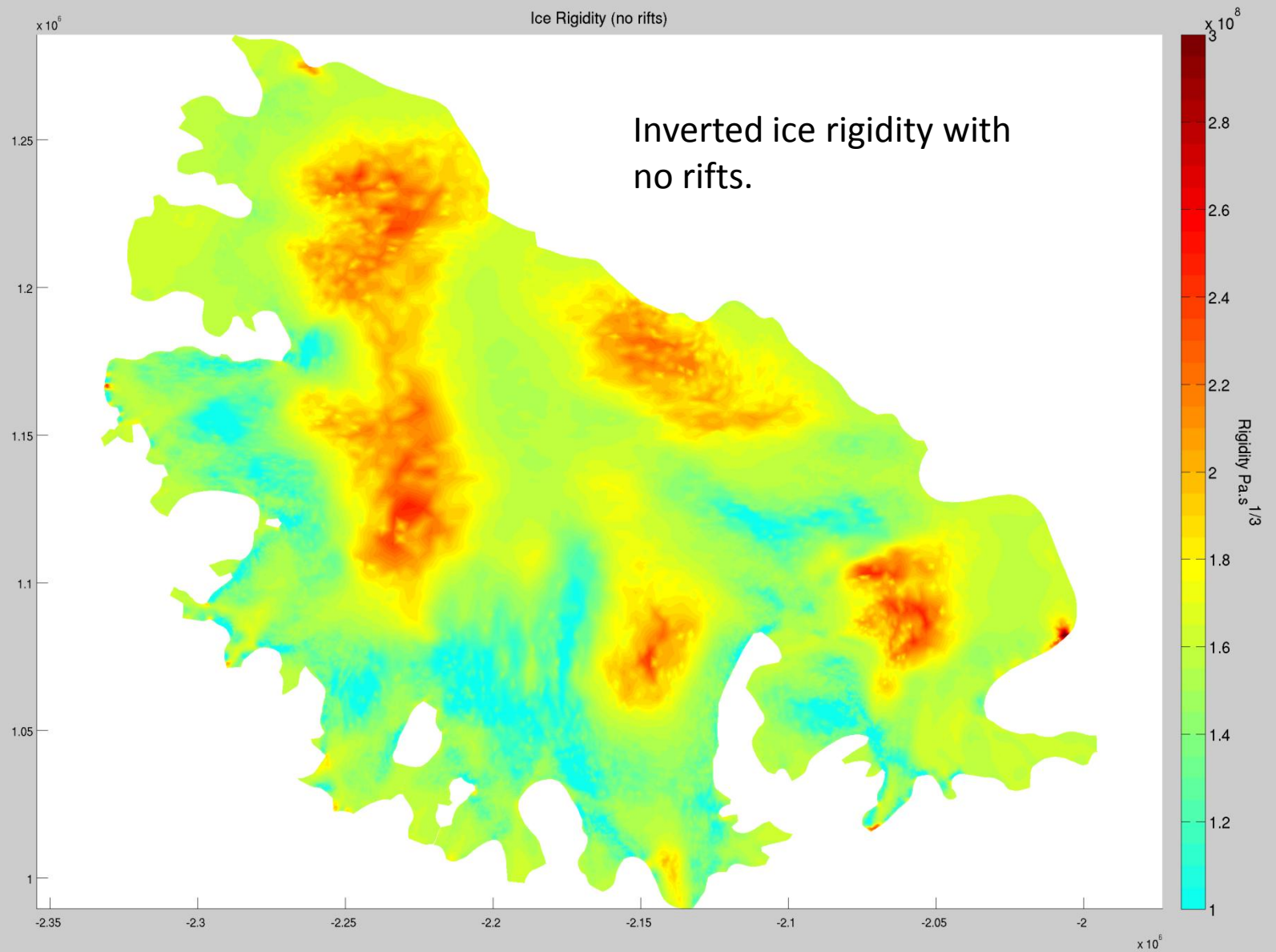




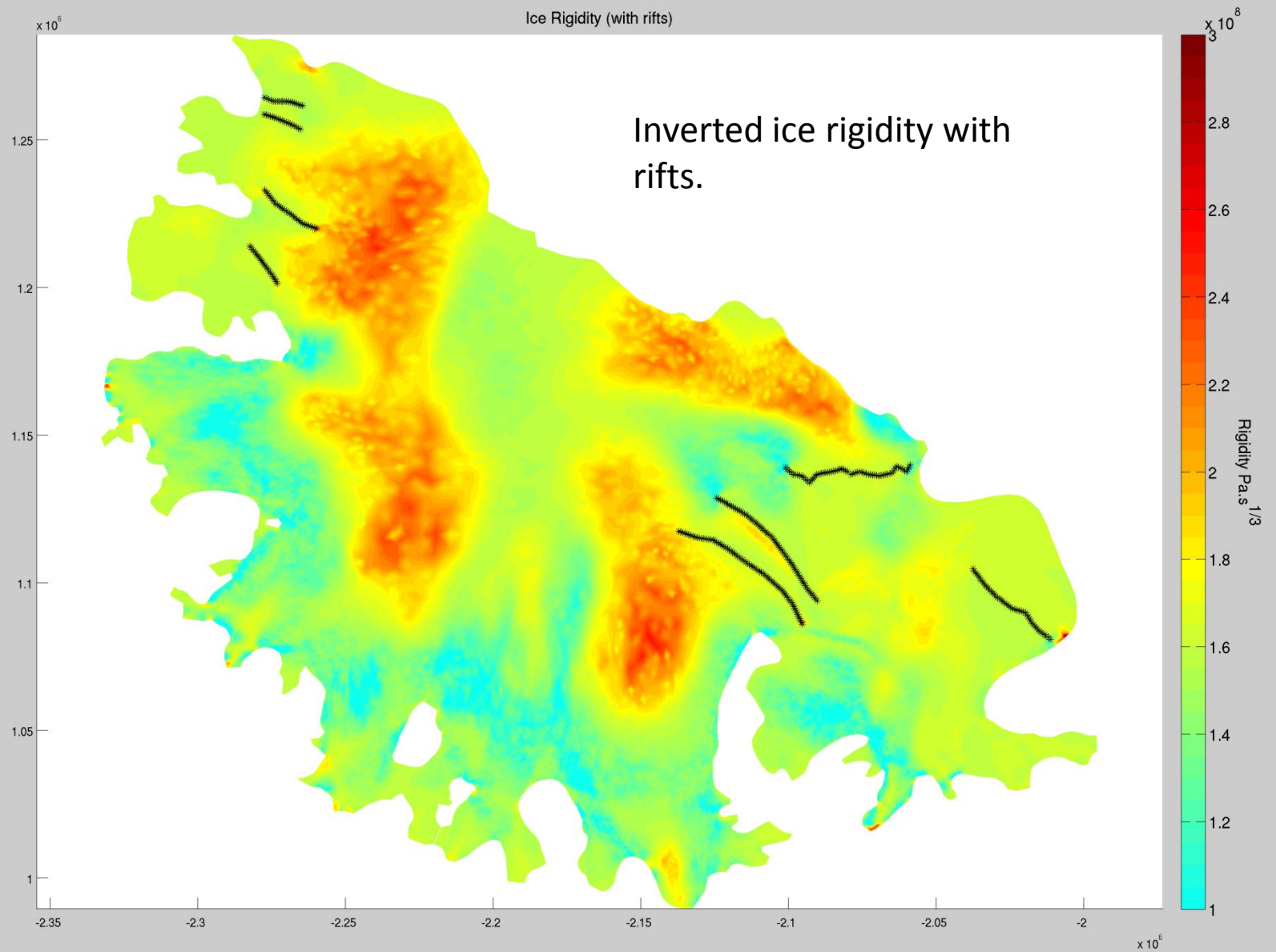
With Rifts











# 5 Conclusions.

- Rifts and faults can be modeled using contact mechanics principles. Stabilization of “wiggling” effect possible using melange fraction.
- Ice flow models can accurately account for delta-velocity across rifts, and tangential friction between flanks for faults.
- Rifting/Faulting processes can be used in ice rheology inversions.
- New model allows for better ice rheology inversions, where rigidity of ice does not have to accommodate for breakdown in continuum mechanics.